

Development of Hybrid GA-PSO for Optimal Design of Valveless Micropump in Biomedical Application

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A thesis submitted in fulfillment of the requirements for the degree of Master of Science (Microelectronic Engineering)

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DECLARATION OF THESIS Author's full name : AIDA FATEHAH BINTI MOHD SHUKUR Date of birth : 05 JANUARY 1988 : DEVELOPMENT OF HYBRID GA-PSO FOR OPTIMAL Title DESIGN OF VALVELESS MICROPUMP IN BIOMEDICAL APPLICATION Academic Session : 2012 – 2015 I hereby declare that the thesis becomes the property of Universiti Malaysia Perlis (UniMAP) and to be placed at the library of UniMAP. This thesis is classified as: **CONFIDENTIAL** (Contains confidential information Official under the Secret Act 1972)* RESTRICTED (Contains restricted information as specified by the organization where research was done)* **OPEN ACCESS** I agree that my thesis is to be made immediately available as hard copy or on-line open access (full text) I, the author, give permission to the UniMAP to reproduce this thesis in whole or in part for the purpose of research or academic exchange only (except during a period of _____ years, if so requested above). Certified by: SIGNATURE SIGNATURE OF SUPERVISOR (880105-10-5078) DR. NURUL IZZA MOHD NOR (NEW IC NO / PASSPORT NO) (NAME OF SUPERVISOR) Date: Date:

ACKNOWLEDGEMENT

In the name of Allah, most Gracious, most Merciful.

Alhamdulillah, thanks to Almighty Allah S.W.T for giving me a strength, patience and chance to complete my research with the title of "Development of Hybrid GA-PSO for Optimal Design of Valveless Micropump in Biomedical Application".

First and foremost, it is a pleasure to acknowledge several people who have given a big contribution in this research especially to my main supervisor and co-supervisors. I am highly appreciating the effort of Dr. Nurul Izza Mohd Nor as my main supervisor and Dr. Neoh Siew Chin as my ex-main supervisor, the persons who guided me in this research. Thanks for their supervision, great attention, constant guidance, encouragement, continuous advices, sharing their ideas and discussions along the progress of my research. Likewise, thanks to Mrs. Bibi Nadia Taib and Mrs. Norhayati Sabani, my co-supervisors who had given me the inputs, valuable knowledge, support and exposed me to microelectromechanical system (MEMS) area. I really appreciate all of their tireless to read each part of my thesis for multiple times, give input, useful suggestion, and comment that led to write and organize this thesis and improved the thesis presentation.

In addition, I would like to express my sincere appreciation to my beloved friends, Ms. Nur Afifah Ismail, Ms. Izatul Syafina Ishak and Mr. Lim Wei Jer who gave a lot of co-operation, have been very kind and helpful since I started my research until now. Not to forget, I would like to convey my gratitude to other people who directly or indirectly helped me in this research.

I want to extend my thanks to my dear parents Mr. Mohd Shukur B. Dal and Mrs. Rosliah Bt. Samsi and my beloved brothers and sisters Ain Syuhadah, Nur Ashiqin, Khairul Muttaqin, Muhd Ikmal Hakimi and Rabiatul Adawiah for their prayer, endless support, understanding, patience and sacrifice to complete my research.

Last but not least, special thanks to Universiti Malaysia Perlis (UniMAP), School of Microelectronic Engineering and Centre for Graduate Studies (CGS) for giving me opportunity, encouragement and as well as gave briefings to complete my research.

Finally, I would like to acknowledge the support given by Ministry of Higher Education Malaysia (MOHE) as my financial sponsor in the period of my studies and for funding the research based on FRGS (Grant no. 9003-00261) and FRGS-KETTHA (Grant no. 9003-00349).

AIDA FATEHAH MOHD SHUKUR

TABLE OF CONTENTS

DECLARATION OF THESIS	i
ACKNOWLEDGEMENT	ii
TABLE OF CONTENTS	iv
LIST OF TABLES	viii
LIST OF FIGURES	ix
LIST OF ABBREVIATIONS	xii
LIST OF SYMBOLS	xiv
ABSTRAK	xvi
LIST OF TABLES LIST OF FIGURES LIST OF ABBREVIATIONS LIST OF SYMBOLS ABSTRAK ABSTRACT CHAPTER 1: INTRODUCTION	xvii
CHAPTER 1: INTRODUCTION	1
1.1 Overview of Micropumps	1
1.2 Problem Statement	4
1.3 Research Objectives	5
1.4 Research Scope	6
1.5 Thesis Outline	7

CHAPTER 2: LITERATURE REVIEW		9
2.1	Introduction	9
2.2	Classification of Micropumps	9
	2.2.1 Mechanical Pumps	11
	2.2.1.1 Electrostatic Actuator	11
	2.2.1.2 Piezoelectric Actuator	12
	2.2.1.3 Bimetallic Actuator	13
	2.2.1.4 Electromagnetic Actuator	14
	2.2.1.5 Thermopneumatic Actuator	15
	2.2.1.6 Shape Memory Alloy (SMA) Actuator	16
	2.2.1.7 Displacement Pumps	18
	2.2.1.8 Dynamic Pumps	21
	2.2.2 Non-Mechanical Pump	23
2.3	Fundamental Theory of Valveless Micropump	25
	2.3.1 Concept of Valveless Micropump	25
	2.3.2 Working Principle	27
	2.3.3 Theoretical and Dimensional Analysis of Micropump Diaphragm	28
© Inis	2.3.4 Theoretical and Dimensional Analysis of Diffuser/Nozzle Element	30
	2.3.5 Review of Valveless Micropumps	33
2.4	Drug Delivery System (DDS)	39
2.5	Introduction of Artificial Intelligence (AI)	43
2.6	Artificial Intelligence Based Optimization	44
	2.6.1 Artificial Neural Network (ANN)	44
	2.6.2 Genetic Algorithm (GA)	46
	2.6.3 Ant Colony Optimization (ACO)	50

		2.6.4 Particle Swarm Optimization (PSO)	51
		2.6.5 Cuckoo Search (CS)	54
	2.7	Hybrid Optimization Based on Implementation of GA and PSO	55
	2.8	Review for Optimization of Micropumps with Implementation of AI	57
	2.9	Chapter Summary	60
СНАРТЕ	ER 3: 1	Introduction Flow of Research Parameter Setup 3.3.1 Design Variables	61
	3.1	Introduction	61
	3.2	Flow of Research	61
	3.3	Parameter Setup	62
		3.3.1 Design Variables	64
		3.3.2 Specification Requirement	68
	3.4	Fitness Functions Evaluation	70
	3.5	Optimization of Valveless Micropump	73
		3.5.1 GA Optimization Modelling	74
		3.5.2 PSO Optimization Modelling	78
		3.5.3 HPSO-GA Optimization Modelling	82
~	3.6	ANSYS Simulation Setup	86
	3.7	Chapter Summary	90
СНАРТЕ	CR 4: 1	RESULTS AND DISCUSSION	91
	4.1	Introduction	91
	4.2	Simulation Results of GA Optimization	91
		4.2.1 Best Chromosomes of GA Optimization	91
		4.2.2 GA Optimization Performance	93

4.3	Simulation Results of PSO Optimization	96
	4.3.1 Best Particles of PSO Optimization	96
	4.3.2 PSO Optimization Performance	98
4.4	Simulation Results of HPSO-GA Optimization	101
	4.4.1 Best Individuals of HPSO-GA Optimization	101
	4.4.2 HPSO-GA Optimization Performance	102
4.5	Comparison Results of Optimization Methods	105
4.6	Valveless Micropump Performance Summary	109
4.7	Summary	116
CHAPTER 5: CONCLUSIONS AND FUTURE WORK		
5.1	Conclusion	117
5.2	Limitation and Assumption	119
5.3	Recommendation and Future work	119
5.4	Novelty and Contribution	120
	.6	
REFERENCES		121
APPENDIX A		130
APPENDIX B		133
APPENDIX C		136
LIST OF PUBI	LICATIONS	137

LIST OF TABLES

No.		Page
2.1	Summary of valveless micropumps.	38
2.2	Review of AI-based micropump optimization.	59
3.1	Synthesis setup of design variables.	65
3.2	Material properties.	67
3.3	Specification requirement for the micropump optimization.	68
3.4	Operation parameters of GA.	77
3.5	Operation parameters of PSO.	79
3.6	Operation parameters of GA. Operation parameters of PSO. Operation parameters of HPSO-GA.	83
4.1	GA optimized design variables for valveless micropump.	92
4.2	Specification value of the best chromosomes for micropump performance using GA optimization.	93
4.3	Fitness value of each function in intial generation and 15 th generation of GA optimization.	95
4.4	PSO optimized design variables for valveless micropump.	97
4.5	Specification value of the best particles for micropump performance using PSO optimization.	97
4.6	Fitness value of each function in intial iteration and 15 th iteration of PSO optimization.	99
4.7	HPSO-GA optimized design variables for valveless micropump.	101
4.8	Specification value of the best individuals for micropump performance using HPSO-GA optimization.	102
4.9	Fitness value of each function in intial iteration and 15 th iteration of HPSO-GA optimization.	103
4.10	Optimized design variables for valveless micropump.	105
4.11	Specification value of the best individuals for micropump performance.	106
4.12	Comparison of AI-based micropump optimization.	114
4.13	Comparison of ANN-GA, GA, PSO and HPSO-GA.	114

LIST OF FIGURES

No.	Pa	age
2.1	Classification of micropumps based on the pumping principle and actuation mechanism.	10
2.2	Electrostatic micropump (Nguyen & Wereley, 2002a).	12
2.3	Piezoelectric micropump (Nguyen & Wereley, 2002a).	13
2.4	Bimetallic micropump (Zou, Ye, Zhou & Yang, 1997).	14
2.5	Electromagnetic micropump (Nisar, Afzulpurkar, Mahaisavariya & Tuantranont, 2008).	15
2.6	Thermopneumatic micropump (Nisar, Afzulpurkar, Mahaisavariya & Tuantranont, 2008).	16
2.7	SMA micropump (Nisar, Afzulpurkar, Mahaisavariya & Tuantranont, 2008).	17
2.8	A cantilever type check-valve micropump.	19
2.9	Schematic diagram of a rotary micropump driven by electromagnetic actuation proposed by Ahn & Allen (1995). Stator, rotor and coils were fabricated by using electroplating of Permalloy and obtained pumping rate is about 24 μ L/min at 5000 rpm (Ahn & Allen, 1995).	19
2.10	Peristaltic displacement micropump with three pump chambers in series developed by Smiths, 1990. The pump is made from an etched silicon substrate bonded between two glass plates. Fluid flow from the inlet at left to the outlet at right.	21
2.11	MHD micropump (Ashraf, Tayyaba & Afzulpurkar, 2011).	24
2.12	Valveless micropump.	27
2.13	Pumping principle of a valveless micropump.	28
2.14	Deflected diaphragm of micropump.	30
2.15	Two-dimensional schematic of diffuser/nozzle element of valveless micropump.	31
2.16	Fabricated valveless micropump proposed by Olsson (1998).	34
2.17	3D overview of the PDMS valveless micropump; a) single chamber,	36

2.18	(Borenstein, 2009).	40
2.19	Block diagram of drug delivery systems, DDS (Ashraf, Tayyaba, Afzulpurkar & Nisar, 2010).	40
2.20	Schematic view of DDS with a bottom view of the assembled device proposed by Matteucci et al. (2008).	42
2.21	Natural neuron.	45
2.22	a) Artificial neuron, b) General structure of multilayer of ANN.	46
2.23	General schematic of GA as a flow chart.	47
2.24	General schematic of GA as a flow chart. Binary string representation of two point crossover.	48
2.25	Binary string representation of three point mutation.	49
2.26	Interaction of the particles (birds) while learning from their own experience and gradually the population member's move into better regions of the search space.	52
2.27	General schematic of PSO as a flow chart.	53
3.1	The flow of overall stage in this research.	62
3.2	Cross-section view of valveless micropump.	63
3.3	3D schematic of planar diffuser/nozzle of valveless micropump.	64
3.4	Process flow of optimization method for valveless micropump using GA.	76
3.5	Process flow of optimization method for valveless micropump using PSO.	78
3.6	Process flow of optimization method for valveless micropump using HPSO-GA.	85
3.7	ANSYS process flow for the design and simulation analysis of micropump.	86
3.8	Model of valveless micropump and micropump chamber created in ANSYS DesignModeler; a) isometric view of valveless micropump, b) cross-section view of valveless micropump, c) isometric view of micropump chamber, d) cross-section view of micropump chamber.	87
3.9	a) Meshed model of valveless micropump, b) Meshed model of micropump chamber.	88
3.10	Micropump chamber in ANSYS CFX-Pre with inlet at left side and outlet at right side.	89

4.1	Graph of fitness value for GA optimization.	94
4.2	Distribution of chromosomes for GA optimization in 1 st , 5 th , 8 th and 15 th generation.	95
4.3	Graph of fitness value for PSO optimization.	98
4.4	Distribution of particles of PSO optimization in 1 st , 5 th , 8 th , and 15 th iteration.	100
4.5	Graph of fitness value for HPSO-GA optimization.	103
4.6	Distribution of particles for HPSO-GA optimization in 1 st , 5 th , 8 th , and 15 th iteration.	104
4.7	Graph of fitness value for GA, PSO and HPSO-GA optimization.	107
4.8	Deformation curve of micropump diaphragm.	108
4.9	Distribution of chromosomes and particles for GA, PSO and HPSO-GA optimization in 15 th iteration.	109
4.10	Resonant frequency of micropump diaphragm.	111
4.11	Velocity vectors and flow moving in the pump chamber for HPSO-GA best individual. Arrows indicate the direction and relative magnitude of the velocity.	112
4.12	Illustrates the correlation between the net flow rate and back pressure for GA, PSO, and HPSO-GA optimization.	113
4.13	Back pressure for the best individuals provided by HPSO-GA optimization.	113

LIST OF ABBREVIATIONS

 μTAS Micro Total Analysis Systems

Three - Dimensional 3D

ABC Artificial Bee Colony

ACO **Ant Colony Optimization**

AFSA Artificial Fish Swarm Algorithm oy original copyright

ΑI Artificial Intelligence

ANN Artificial Neural Network

CFD Computational Fluid Dynamic

CS Cuckoo Search

DDS Drug Delivery System

Differential Evolution DE

Deep Reactive Ion Etching **DRIE**

EHD Electrohydrodynamic

FA Firefly Algorithm

Finite Element Analysis **FEA**

GA Genetic Algorithm

Genetic Algorithm for Design Optimization **GADO**

GAMA Genetic Algorithm for Model Adaptation

HPSO-GA Hybrid PSO and GA

HRA Harmonic Response Analysis

ICPF Ionic Conductive Polymer Film

IDT **Interdigitated Transducers**

LCD Liquid Crystal Display

Lightweight Piezo - Composite Actuators **LIPCAs**

LOC Lab-On-A-Chip

Micro-Electro-Mechanical Systems **MEMS**

MHD Magnetohydrodynamic

NSGA-II Non-Dominated Sorted GA

Poly-Dimethylsiloxane **PDMS**

PSO Particle Swarm Optimization

PZT Piezoelectric Zirconate Titanate

QoS Quality-of-Service

SMA

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TiNi

LIST OF SYMBOLS

 \boldsymbol{A} Narrowest cross-section area Constant factors c_1 Constant factors c_2 Diffuser d DThroat width \boldsymbol{E} Young's Modulus F1Fitness function for total deformation *F*2 Fitness function for strain energy *F3* Fitness function for equivalent stress F4 Fitness function for resonant frequency F5 Fitness function for net flow rate Fitness function for velocity *F*6 Fitness value for the specification m F_{m} $Fm_{average}$ Average value of specification m Total fitness value F_{tot} Best global value gbest **ITER** Current iteration iter_{ma} Maximum iteration Length of diffuser/nozzle element LNumber of inputs mNozzle n P Distributed pressure Best position in the current population p_{best} P_{m} Mutation probability Particle position

pos

 pos_k^i Position of particle *i* in the dimensional search space at *k* iteration

 P_x Crossover probability

Q Flow rate

 $Q_{d/n}$ Flow rate at diffuser/nozzle element

 Q_{net} Net flow rate of micropump

R Radius of the diaphragm

rand Randomly generated value

t Diaphragm thickness

 t_c Pumping chamber thickness

V Fluid velocity

v Material Poisson's ratio

 V_0 Dead volume

vel Velocity of particle

 vel_k^i Velocity of particle *i* in the dimensional search space at *k* iteration

w Inertia weight

 W_m Weight for specification m

 w_{max} Maximum value of weight

 w_{min} Minimum value of weight

y_{max} Diaphragm deformation

α Penalty value

 ΔP Pressure drop

 ΔV Stroke volume

 ε Compression ratio

 η Efficiency ratio

 θ Opening angle for the diffuser/nozzle element

Pressure loss coefficient

 ρ Fluid density

Pembangunan Hybrid GA-PSO untuk Reka Bentuk Pam Mikro Tanpa Injap yang Optimum didalam Aplikasi Bioperubatan

ABSTRAK

Pam mikro adalah salah satu komponen yang paling penting didalam bendalir mikro dan sistem mikroelektromekanikal (MEMS) kerana ia mempunyai kebolehan untuk mengangkut bendalir dalam skala mikro dan dapat mengawal kadar aliran dengan tepat dan cekap. Pelbagai reka bentuk dan pendekatan telah dicadangkan untuk membangunkan pam mikro yang mempunyai prestasi yang tinggi. Tesis ini menunjukkan kaedah pengoptimuman untuk pam mikro tanpa injap dengan menggunakan perlaksanaan pendekatan kepintaran tiruan (AI). Pam mikro tanpa injap ini direka bentuk dengan sebuah diafragma, ruangan pengepaman dan elemen penyebaran/penyedutan berfungsi sebagai saluran masuk dan saluran keluar dengan dimensi keseluruhan adalah $5 \times 1.75 \times 5 \text{ mm}^3$. Perlaksanaan struktur pengoptimuman pam mikro tanpa injap adalah penting untuk menentukan kadar aliran bersih yang maksimum yang boleh dihasilkan oleh pam mikro dengan penggunaan kuasa yang rendah. Bagi menentukan prestasi reka bentuk pam mikro, jumlah perubahan, ketegangan tenaga, jumlah tekanan, frekuensi resonasi untuk diafragma, halaju bendalir dan kadar aliran pam mikro dikaji. Tekanan belakang yang optimum untuk diafragma pam mikro tanpa injap diperolehi memalui hasil penilaian. Pengoptimuman dilakukan untuk memaksimumkan jumlah perubahan, halaju, kadar aliran bersih dan meminimumkan ketegangan tenaga, jumlah tekanan dan frekuensi resonasi pam mikro. Bagi menilai prestasi pam mikro untuk aplikasi perubatan, fungsi kesesuaian dibentuk menilai pembolehubah reka bentuk struktur pam mikro. menggabungkan alat pengoptimum dengan perisian elemen analysis terhad (FEA) iaitu ANSYS Workbench, simulasi dan model pengoptimuman boleh dibina untuk mencari parameter reka bentuk pam mikro yang paling optimum. Pam mikro tanpa injap yang ditunjukkan dioptimumkan dengan tiga kaedah pengoptimuman yang berbeza iaitu algoritma genetik (GA), pengoptimuman sekumpulan zarah (PSO) dan kacukan/hibrid PSO dengan GA (dinotasikan sebagai HPSO-GA). Hasil simulasi yang diperolehi di bandingkan dan dikaji untuk ketiga-tiga cara pengoptimuman. Dari kajian yang dijalankan, Hasil simulasi menunjukkan bahawa HPSO-GA yang dicadangkan memberikan penyelesaian yang lebih baik untuk prestasi pam mikro. Keputusan yang diperolehi melalui model yang dibangunkan daripada pengoptimuman HPSO-GA menyatakan bahawa jumlah perubahan maksimum diafragma adalah 8.4797 µm dengan 8 kPa tekanan penggerakkan dan kadar aliran bersih yang optimum adalah 3.89 mL/min dengan halaju 4.796 m/s.

Development of Hybrid GA-PSO for Optimal Design of Valveless Micropump in Biomedical Application

ABSTRACT

Micropumps are one of the most important components of microfluidic and microelectromechanical system (MEMS) because of the ability to transport fluids in microscale and have the control of the flow rate in an accurate and efficient manner. Various designs and approaches are suggested in order to develop a high performance micropump. This thesis presents the optimization method of valveless micropump utilizing the implementation of artificial intelligence (AI) approaches. The valveless micropump is designed with a diaphragm, pumping chamber and diffuser/nozzle elements functions as inlet and outlet with the outer dimension of $5 \times 1.75 \times 5$ mm³. The implementation of structure optimization of valveless micropump is important in order to determine the maximum net flow rate that can be generated by the micropump with low power consumption. In order to determine the performance of the micropump, the total deformation, strain energy, equivalent stress, resonant frequency for diaphragm, fluid velocity and net flow rate of the micropump are investigated. Optimum back pressure for the diaphragm of valveless micropump was obtained through the result assessment. Optimization is done to maximize the total deformation, velocity, net flow rate and minimize the strain energy, equivalent stress and resonant frequency of the micropump. In order to evaluate the performance of the micropumps for medical application, a fitness function is constructed to evaluate the design variables of micropump structure. By executing optimization tools in conjunction with finite element analysis (FEA) software ANSYS workbench, the simulation and optimization model is able to find out the optimum micropump design parameters. The presented valveless micropumps are optimized in three deferent optimization methods which are genetic algorithm (GA), particle swarm optimization (PSO) and hybrid PSO with GA (denoted as HPSO-GA). Simulation results obtained are compared and investigated for the three optimization methods. From the research, simulation results show that the proposed HPSO-GA provide better solution for micropump performance. Results obtained through the developed model of HPSO-GA optimization stated that the maximum total deformation of the diaphragm is 8.4797 µm with 8 kPa actuation pressure and optimum net flow rate is 3.89 mL/min with velocity of 4.796 m/s.

CHAPTER 1

INTRODUCTION

1.1 Overview of Micropumps

Over the years, development of miniaturized microelectromechanical system (MEMS) devices becomes essential and critical issues to microfluidics applications. Due to the size miniaturization, microfluidics devices have the ability to develop unique transport properties and provide the capability of parallel processing and high throughput. The fields of microfluidics expand with the development of MEMS devices and its application including in lab-on-a-chip (LOC), micro total analysis systems (µTAS), chemical analysis systems, bio-MEMS, medical application and other micro devices (Ashraf, Tayyaba & Afzulpurkar, 2011; Laser & Santiago, 2004; Nguyen, Huang & Chuan, 2002; Yamahata et al., 2005). Advantages of microfluidics in MEMS are very small sizes, low power consumption, high precision, better performance, lower costs, disposability and can be integrated with electronics devices.

Recently, investigations into methods of using microfluidics and MEMS application for medical application and drug delivery systems (DDS) have been expanded (Nuxoll, 2013; Zhang & Nagrath, 2013). MEMS applications are utilized in medical applications and DDS to design the devices and instruments for medical used such as microreservoir, microactuator, microneedle, microvalve, and micropump. In contrast to other microfluidics devices, micropump is a component that has been designed according to its application and requirement such as for microelectronic

cooling, micro-space exploration, inkjet printers, chemical injection and especially in medical applications.

Specifically, micropumps are the most important element of MEMS and microfluidics component because of its ability to transport fluids in microscale and to control the flow rate in an accurate and efficient manner. Due to its important role in many microfluidics systems, the outcomes from the constantly building MEMS technology upon microstructures supplies as well as manufacturing systems tend to move to the investigation on micropumps (Anagnostopoulos & Mathioulakis, 2005). The most valuable features of micropumps are miniature of sizes and high precision in controlling fluid have made them very useful in chemotherapy, insulin delivery for diabetic patient and drug dosing for cancer patient (Smits, 1990). Development of micropumps becomes more important due to medical demands in order to transport drug and insulin in micro or nano dosage. In medical application, micropumps are applied to construct DDS that enable enhanced control over the delivery of therapeutic agents (Arora, Prausnitz & Mitragotri, 2008; Martanto et al., 2004; Mousoulis, Ochoa, Papageorgiou & Ziaie, 2011; Zengerle & Richter, 1992). Micropumps have been designed with various types of actuator mechanism used as a device for control on mechanical movement according to the micropump's application. Generally, micropumps can be developed by using several actuation methods such as electrostatic, piezoelectric, electromagnetic, pneumatic, thermopneumatic, bimetallic and shape memory alloy (SMA) actuation (Nisar, Afzulpurkar, Mahaisavariya & Tuantranont, 2008).

The researches on micropumps began since 1970s whereas MEMS-based micropumps have been developed in 1990s (Ashraf, Tayyaba & Afzulpurkar, 2011;

Olsson, 1998; Woias, 2005). Among the earliest development of micropumps was proposed by Thomas & Bessman (1975) in 1975. Thomas & Bessman (1975) used the micropump for implantation into human body. The micropump was actuated by using piezoelectric disc benders and consists of solenoid valve connected to variable pumping chambers. In 1978, Spencer et al. (1978) proposed cylindrical micropump actuated by piezoelectric stainless steel and the body of micropump machined from stainless steel. Tuckerman & Pease (1981) developed micropump used for microelectronics cooling based on liquid-phase chip cooling to consider flow rates of several hundred milliliters per minute. Lintel & Pol (1988) developed reciprocating displacement pump consisting of one and two pump chamber actuated by piezoelectric disc to be used in insulin delivery system. Esashi, Shoji & Nakano (1989) proposed normally closed microvalve and micropump fabricated on a silicon wafer. The normally closed microvalve actuated by piezostack actuator and verified the possibility to use a serial connection of two of those valves with a pressure chamber in between. In the year of 1990, Smits (1990) designed a peristaltic micropump with three active valves actuated by piezoelectric discs. Smits (1990) intended to use the micropump in controlled insulin delivery systems for maintaining diabetic blood sugar levels without frequent needle injections. Zengerle, Richter & Sandmaier (1992) presented a bulk micromachined membrane pump actuated by electrostatic actuator. The micropump consists of two passive check valves, a pump membrane and counterelectrode for electrostatic actuation with outer dimension of $7 \times 7 \times 2 \text{ mm}^3$.

At present, the investigation and development of micropumps become crucial task in research area to produce the high performance micropumps according to its application and requirement. Micropumps can be classified in two major categories, which are displacement pump and dynamic pump. The description about the

classification, concept and working principle of micropumps are explained further in Chapter 2.

1.2 Problem Statement

Micropumps as the actuation mechanism in microfluidics systems has been the issue in many researches area to determine its achievement in mobility of fluid, low power consumption and improved accuracy (Amirouche, Zhon & Johnson, 2009). In order to apply micropumps for medical uses, several factors must be taken into account such as biocompatibility of materials, effectiveness, and efficiency of the pump. Besides that, features of a micropump must also be considered such as actuation method, working principles, construction and performance of micropump parameters. Basic components of micropumps consist of pumping chamber, diaphragm, diffuser/nozzle element, inlet and outlet. These components play an important role to attain the high performance of micropumps. The micropumps diaphragm needs to deflect as large as a can to perform stroke volume and high compression ratio. Whereas the effectiveness and efficiency of the flow rectification is obtained based on the net flow rate and dependent on the diffuser/nozzle element design and geometry. In addition, materials of micropumps must have good chemical stability, biocompatibility, elasticity and economics scale (low cost).

Micropumps have complex design variables and require specific time to develop a pump system with high performance based on its application. In order to make the design of micropumps more systematic and efficient, the optimization tool of micropump variables is suggested. Many theories and methods are used to optimize the

micropumps in order to acquire the high performance of micropumps. To design a micropump is a critical issue in choosing the optimum parameters to attain high net flow rate in forward direction (which fluid flow from inlet to outlet) with low power consumption and to avoid the fluid flow in reverse direction (which fluid flow from outlet to inlet). Hence, to develop a high performance and low power consumption of micropump, design optimization of micropump is suggested in this research by using the implementation of artificial intelligence (AI) approaches.

1.3 Research Objectives

The main objective of this research is to optimize the design variables of micropump by using AI approaches. In this research, the appropriate dimensions and parameters of the micropump are determined according to the application of the micropump. The other objectives are listed as follow:

- i. To determine the optimum parameters for the micropump according to its application and requirement.
- To generate the optimization of micropump based on genetic algorithm (GA) and particle swarm optimization (PSO) methods.
- iii. To develop a hybrid optimization method used to optimize the micropump design variables.
- iv. To analyze and investigate the performance of micropump.

1.4 Research Scope

In this research, the performance of valveless micropump is studied. This research starts with the determination of the design variables for valveless micropump to be optimized using the implementation of AI methods. The variable parameters of valveless micropump are determined based on its application in medical application. The structure of valveless micropump is designed and simulated using ANSYS Workbench software whereas for the optimization algorithm is developed using MATLAB. This study focuses on GA, PSO and hybrid PSO-GA (denoted as HPSO-GA) optimization tools to optimize the design variables of valveless micropump. Simulation results obtained are compared for the three methods of optimization.

Three types of materials are investigated in this research to analyze the structural performance of the valveless micropump. These materials are silicon, silicon dioxide and stainless steel that have been successfully applied in medical application with the recent growth of drug delivery systems (DDS). Besides, these materials are extensively used as a good biocompatible material. However, a trend towards the use of polymers as substrate materials is growing as polymer materials are widely used in medical application. One of the most popular polymer materials in MEMS is polydimethysiloxane (PDMS). Although PDMS have some advantages and becomes a trend in MEMS fabrication, however this material has not selected to be included in this work. This is because the limitation of PDMS in term of the structure. PDMS is a soft structure and has the tendency to swell in most of the organic solvents besides its low Young's Modulus (several hundreds kPa) resulting in a bulging of the structures for applied pressure differences larger than 1 bar (0.1 MPa). Furthermore, the surface of