



**U MAP**

**SCHOOL OF MECHATRONIC ENGINEERING  
UNIVERSITI MALAYSIA PERLIS,  
02600 JEJAWI, ARAU, PERLIS, MALAYSIA**

**ICoMMS 2009**

**International Conference on MAN-MACHINE SYSTEMS  
(ICoMMS 2009)  
11-13, October 2009**

**COPYRIGHT TRANSFER AGREEMENT**

(This Copyright Transfer Form is mandatory and has to be filled up, signed and attached to each paper)

**Title of paper:**

**Developing an Autonomous Mobile Robot and a Study of Navigation towards Nonholonomic problems**

**Paper Number: 59914 7314**

**ICoMMS 2009 No.: 1**

**Author (s): Rudzuan Mohd Nor, Hazry Desa, Mohd Sofian M.Rosbi, R. Nagarajan**

I/We hereby declare that the material being presented by me or by my co-author is my/our original work, and does not contain or include any material taken from other copyrighted sources. Whenever such material has been included, it has been clearly referred and identified and due acknowledgement is given at the appropriate places in the manuscript.

I/We also grant and assign exclusively to School of Mechatronic Engineering (SME), Universiti Malaysia Perlis (UniMAP), Perlis, Malaysia, any and all rights of whatsoever kind or nature now or hereafter protected by Copyright Laws of the Government of Malaysia. This assignment gives SME, UniMAP the right to register copyright to the paper in its name as claimant and to publish the above titled paper in any print or electronic medium.

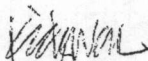
I/We hereby authorize the publishers who have been awarded the work by the SME, UniMAP in the publication of ICoMMS 2009 Conference Proceedings.

We, the author and co-authors, authorize the undersigned who have been corresponding with ICoMMS 2009 Conference authorities during the processing of paper to sign in favor of every one of us.

**Name of Corresponding author: Mohd Rudzuan Bin Mohd Nor**

**Address: No.9 Jalan Sri Pauh 3, Taman Sri Pauh, 02600 Arau, Perlis**

**Email: rudzuan@unimap.edu.my**

**Signature:** 

**Date: 11.Aug.2009**