# A Study on Reliability of an Efficient Technique 

Jamshad Ahmad, Faizan Hussain<br>Department of Mathematics, Faculty of Sciences<br>University of Gujrat<br>Gujrat, Pakistan

Received: 2 October 2013; Accepted: 22 November 2013


#### Abstract

In this paper, two reliable modifications of Variational Iteration Method (VIM) are tested for two nonlinear mathematical problems like Emden-Fowler Equation and Lane-Emden Equation, which arises in diverse fields of physics. It has been observed that these modifications are very efficient and reliable for the solution of the non-linear problems. Numerical results represent the reliability, effectiveness and efficiency of the proposed modifications.


Keywords: Singular differential equation, Emden-Fowler Equation, Lane-Emden Equation, Variational iteration method.

PACS: 35F25, $35 F 31$.

## 1 Introduction

Most of the problems in natural and engineering sciences are modeled by differential equations. These equations arise in various scientific models such as the fluid mechanics, chemical reaction diffusion, propagation of shallow water waves, Schrodinger equation models. To solve such models, a large amount of work has been invested several techniques [1-10] including Homotopy Perturbation, Methods of Characteristic, Multi Grid, Periodic Multi Grid Wave form, Riemann invariants, Finite Difference, Polynomial and Non-polynomial Spline, Variational of Parameter, Sink Galerkin, Parameter Expansion, Energy Balance, Homotopy analysis have been developed for the solution of the natural and engineering problems. Most of the techniques have their limitations and encounter the inbuilt deficiencies like linearization, limited convergence, divergent results, unrealistic assumptions and a lot of computational work.

Recently, Ghorbani et. al. [11] introduced He's polynomials by splitting the non-linear term. He's polynomial are calculated from He's Homotopy Perturbation method [12-14]. More recently,

[^0]Noor and Mohyud-Din [15,16] combined correction functional and He's polynomials of the Variational Iteration Method (VIMHP) and applied this reliable modified form of VIM to a wide class of physical problems. The basic motive of the present study is the implementations of the reliable modifications of Variational Iteration Method to the singular initial value problems.

## 2 Analysis of Variational Iteration Method (VIM)

To elucidate the basic of the variational Iteration Method (VIM), we consider the differential equation in the general form

$$
\begin{equation*}
L u+N u=f(x) \tag{1}
\end{equation*}
$$

where $L$ is a linear operator, $N$ is non-linear operator and $f(x)$ is source term respectively. According to variational iteration method, the correction functional of Eq. (1) can be written as,

$$
\begin{equation*}
u_{n+1}(x)=u_{n}(x)+\int_{0}^{x} \lambda(\tau)\left(L u_{n}(\tau)+N \tilde{u}_{n}(\tau)-f(\tau)\right) d \tau \tag{2}
\end{equation*}
$$

where $\lambda$ is a Lagrange multiplier, which can be identified optimally via variational theory. After determined the Lagrange multiplier, the successive approximation $u_{n+1}, n \geq 0$, of the solution $u$ will be readily obtained by using determined Lagrange multiplier and any selective function $u_{0}$. Consequently, the solution is given by

$$
\begin{equation*}
u(x)=\operatorname{Lim}_{n \rightarrow \infty} u_{n}(x) \tag{3}
\end{equation*}
$$

## 3 Variational Iteration Method using He's Polynomials (VIMHP)

Variational Iteration Method using He's polynomials is a modified form of Variational Iteration Method. This modification is obtained by coupling of correction functional of Variational Iteration Method with He' Polynomials and is given by

$$
\begin{equation*}
\sum_{n=0}^{\infty} p^{(n)} u_{n}(x)=u_{0}(x)+p \int_{0}^{x} \lambda\left(\sum_{n=0}^{\infty} p^{(n)} L\left(u_{n}\right)+\sum_{n=0}^{\infty} p^{(n)} N\left(\tilde{u}_{n}\right)\right) d \tau-\int_{0}^{x} \lambda f(\tau) d \tau \tag{4}
\end{equation*}
$$

By comparing the like indexes of $p$, give solution of various order.

## 4 Variational Iteration Method using Adomian's Polynomials (VIMAP)

Variational Iteration Method using Adomian's Polynomials is another modified form of Variational Iteration Method. This Modification is obtained by coupling of correction functional of Variational Iteration Method with Adomian's Polynomials and is given by

$$
\begin{equation*}
u_{n+1}(x)=u_{n}(x)+\int_{0}^{x} \lambda(\tau)\left(L u_{n}(\tau)+\sum_{n=0}^{\infty} A_{n}-f(\tau)\right) d \tau \tag{5}
\end{equation*}
$$

where $A_{n}$, are called Adomian's Polynomials which can be generated for all type of non-linearity, and determined by the algorithm defined in [17].

$$
\begin{aligned}
& A_{0}=F\left(u_{0}\right) \\
& A_{1}=u_{1} F^{\prime}\left(u_{0}\right) \\
& A_{2}=u_{2} F^{\prime}\left(u_{0}\right)+\frac{u_{1}^{2}}{2!} F^{\prime \prime}\left(u_{0}\right) \\
& A_{3}=\frac{u_{1}^{3}}{3!} F^{\prime \prime \prime}\left(u_{0}\right)+u_{1} u_{2} F^{\prime \prime}\left(u_{0}\right)+u_{3} F^{\prime}\left(u_{0}\right) \\
& \vdots
\end{aligned}
$$

## 4 Analysis of VIM for Singular initial value Problem

Consider the singular initial value problem

$$
\begin{equation*}
y^{\prime \prime}(x)+\frac{k}{x} y^{\prime}(x)+g(x) y(x)=f(x) \tag{6}
\end{equation*}
$$

Subject to the conditions

$$
y(0)=0, y^{\prime}(0)=1 .
$$

According to variational Iteration Method, the correction functional of Eq. (6) can be written as,

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x} \lambda(x, \tau)\left(y_{n}^{\prime \prime}(\tau)+\frac{2}{\tau} y_{n}^{\prime}(\tau)+\frac{k-2}{\tau} \tilde{y}_{n}^{\prime}(x)+g(\tau) \tilde{y}_{n}(\tau)-f(\tau)\right) d \tau \tag{7}
\end{equation*}
$$

Where $\lambda$ is called general Lagrange multiplier, which can be identified optimally via variational theory, and $\tilde{y}_{n}$, is considered as restricted Variations so, taking $\delta$ on both sides, we get

$$
\delta y_{n+1}(x)=\delta y_{n}(x)+\delta \int_{0}^{x} \lambda\left(y_{n}^{\prime \prime}(\tau)+\frac{2}{\tau} y_{n}^{\prime}(\tau)+\frac{k-2}{\tau} \tilde{y}_{n}^{\prime}(x)+g(\tau) \tilde{y}_{n}(\tau)-f(\tau)\right) d \tau,(8)
$$

The Lagrange multiplier can be identified via variational theory.

$$
\lambda(x, \tau)=\frac{\tau^{2}}{x}-\tau
$$

Now, Eq. (5) becomes,

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\tau y_{n}^{\prime \prime}(\tau)+k y_{n}^{\prime}(\tau)+\tau g(\tau) y_{n}(\tau)-\tau f(\tau)\right) d \tau, n \geq 0 \tag{9}
\end{equation*}
$$

Consequently, the solution is given by

$$
y(x)=\operatorname{Lim}_{n \rightarrow \infty} y_{n}(x)
$$

## 5 Numerical Applications

### 5.1 Example

Consider the classical Emden-Fowler equation of the second kind

$$
\begin{equation*}
\frac{d^{2} y}{d x^{2}}+\frac{2}{x} \frac{d y}{d x}+\alpha x^{m} y^{r}=0 \tag{10}
\end{equation*}
$$

subject to the initial conditions,

$$
y(0)=1, y^{\prime}(0)=0 .
$$

where $\alpha, m$ and $r$ are constants.

## VIMHP

According to VIM, the correction functional for the Eq. (10) can be written as

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x} \lambda(x, \tau)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}+\alpha \tau^{m} \tilde{y}_{n}^{r}(\tau)\right) d \tau \tag{11}
\end{equation*}
$$

The Lagrange Multiplier can be identified via variational theory.

$$
\lambda(x, \tau)=\frac{\tau^{2}}{x}-\tau
$$

Now Eq. (11) becomes

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}+\alpha \tau^{m} y_{n}^{r}(\tau)\right) d \tau \tag{12}
\end{equation*}
$$

According to VIMHP, Eq. (12) can be written as,

$$
\begin{aligned}
& \sum_{n=0}^{\infty} p^{n} y_{n}(x)=y_{0}+p \int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left[\sum_{n=0}^{\infty} p^{n} \frac{d^{2} y_{n}}{d \tau^{2}}+\frac{2}{\tau} \sum_{n=0}^{\infty} p^{n} \frac{d y_{n}}{d \tau}+\alpha \tau^{m} \sum_{n=0}^{\infty} p^{n} y_{n}^{r}\right] d \tau \\
& \sum_{n=0}^{\infty} p^{n} y_{n}(x)=1+p \int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left[\sum_{n=0}^{\infty} p^{n} \frac{\tau d^{2} y_{n}}{d \tau^{2}}+2 \sum_{n=0}^{\infty} p^{n} \frac{d y_{n}}{d \tau}+\alpha \tau^{m+1} \sum_{n=0}^{\infty} p^{n} y_{n}^{r}\right] d \tau
\end{aligned}
$$

for $r=1$,
$\sum_{n=0}^{\infty} p^{n} y_{n}=1+p \int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left[\sum_{n=0}^{\infty} p^{n} \frac{\tau d^{2} y_{n}}{d \tau^{2}}+2 \sum_{n=0}^{\infty} p^{n} \frac{d y_{n}}{d \tau}+\alpha \tau^{m+1} \sum_{n=0}^{\infty} p^{n} y_{n}\right] d \tau$,

Now, comparing the co-efficient of like powers of $p$,

$$
\begin{aligned}
p^{(0)}: \quad y_{0} & =1 \\
p^{(1)}: & y_{1}
\end{aligned}=\int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\alpha \tau^{m+1}\right) d \tau,
$$

$$
\vdots
$$

Therefore,

$$
\begin{align*}
y(x) & =y_{0}+y_{1}+y_{2}+\cdots, \\
& =1-\frac{\alpha x^{m+2}}{(m+3)(m+2)}+\frac{\alpha^{2} x^{2 m+4}}{2(2 m+5)(m+3)(m+2)^{2}}-\cdots, \tag{14}
\end{align*}
$$

This is the same result is as obtained by Chowdhury [18].

## VIMAP

According to VIMAP, Eq. (10) can be written in the form,

$$
\begin{equation*}
y_{n+1}(x)=y_{0}(x)+\int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\frac{\tau d^{2} y_{n}(\tau)}{d \tau^{2}}+2 \frac{d y_{n}}{d \tau}+\alpha \tau^{m+1} \sum_{n=0}^{\infty} A_{n}\right) d \tau \tag{15}
\end{equation*}
$$

The initial approximate solution is reads as

$$
y_{0}=1
$$

Consequently, for $r=1$, we have

$$
\begin{aligned}
& y_{1}=\frac{-\alpha x^{m+2}}{(m+3)(m+2)}, m>-2, \\
& y_{2}(x)=\frac{\alpha x^{2 m+4}}{2(2 m+5)(m+3)(m+2)}, m>-2,
\end{aligned}
$$

And so on. Finally, we have

$$
\begin{equation*}
y(x)=1-\frac{\alpha x^{m+2}}{(m+3)(m+2)}+\frac{\alpha x^{2 m+4}}{2(2 m+5)(m+3)(m+2)^{2}} \cdots, \tag{16}
\end{equation*}
$$

This is the same result as obtained by Chawdhary [18].
Particularly, we obtained the exact solution as
For $m=0$, and $r=0$,

$$
\begin{aligned}
& y_{0}=1 \\
& y_{1}=-\frac{\alpha x^{2}}{6} \\
& y_{2}=0
\end{aligned}
$$

Therefore, the exact solution will be

$$
\begin{equation*}
y(x)=1-\frac{\alpha x^{2}}{6} \tag{15}
\end{equation*}
$$

for $m=0$, and $r=1$,

$$
y_{0}=1, y_{1}=-\frac{\alpha x^{2}}{6}, y_{2}=\frac{\alpha^{2} x^{4}}{120}, y_{3}=-\frac{\alpha^{3} x^{6}}{5040}, \cdots,
$$

Therefore,

$$
\begin{align*}
y(x) & =1-\frac{\alpha x^{2}}{6}+\frac{\alpha^{2} x^{4}}{120}-\frac{\alpha^{3} x^{6}}{5040}+\cdots \\
y(x) & =\frac{1}{x}\left(x-\frac{\alpha x^{3}}{6}+\frac{\alpha^{2} x^{5}}{120}-\frac{\alpha^{3} x^{7}}{5040}+\cdots\right) \\
& =\frac{1}{\sqrt{\alpha} x}\left(\sqrt{\alpha} x-\frac{\alpha^{\frac{3}{2}} x^{3}}{6}+\frac{\alpha^{\frac{5}{2}} x^{5}}{120}-\frac{\alpha^{\frac{7}{2}} x^{7}}{5040}+\cdots\right), \\
y(x) & =\frac{\operatorname{Sin}(\sqrt{\alpha} x)}{\sqrt{\alpha} x} \tag{16}
\end{align*}
$$

for $m=0$, and $r=5$,

$$
\begin{align*}
& y_{0}=1 \\
& y_{1}=-\frac{\alpha x^{2}}{6} \\
& y_{2}=\frac{\alpha^{2} x^{4}}{24}-\frac{3 \alpha^{3} x^{6}}{70}+\frac{17 \alpha^{4} x^{8}}{630}-\frac{59 \alpha^{5} x^{10}}{11550}+\frac{\alpha^{6} x^{12}}{3510} \\
& \vdots \\
& y(x)=\left(1+\frac{\alpha x^{2}}{3}\right)^{-\frac{1}{2}} \tag{17}
\end{align*}
$$

Plot of graphically representation for $r=0,1,5$.


Fig. 1

### 5.2 Example

Consider the non-linear Emden-Fowler Equation

$$
\begin{equation*}
\frac{d^{2} y}{d x^{2}}+\frac{2}{x} \frac{d y}{d x}+\alpha \ln x y^{r}=0, \tag{18}
\end{equation*}
$$

Subject to the conditions

$$
y(0)=1, y^{\prime}(0)=0 .
$$

## VIMHP

According to VIM, the correction functional for the Eq. (18) can be written as

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x} \lambda(\tau)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}+\alpha\left(\tau^{m} \ln \tau\right) \tilde{y}_{n}^{r}\right) d \tau \tag{19}
\end{equation*}
$$

The Lagrange Multiplier can be identified via variational theory.

$$
\lambda(x, \tau)=\frac{\tau^{2}}{x}-\tau
$$

Now Eq. (19) becomes

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}+\alpha\left(\tau^{m} \ln \tau\right) y_{n}^{r}\right) d \tau \tag{20}
\end{equation*}
$$

According to VIMHP, Eq. (20) can be written as,
$\sum_{n=0}^{\infty} p^{(n)} y_{n}(x)=y_{0}+p \int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{d^{2} y_{n}}{d \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} \frac{2}{\tau} \frac{d y_{n}}{d \tau}+\sum_{n=0}^{\infty} p^{(n)} \alpha\left(\tau^{m} \ln \tau\right) y_{n}{ }^{r}\right) d \tau$,
$\sum_{n=0}^{\infty} p^{(n)} y_{n}(x)=1+p \int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{\tau d^{2} y_{n}}{d \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} 2 \frac{d y_{n}}{d \tau}+\sum_{n=0}^{\infty} p^{(n)} \alpha\left(\tau^{m+1} \ln \tau\right) y_{n}{ }^{r}\right) d \tau$,
for $r=1$,
$\sum_{n=0}^{\infty} p^{(n)} y_{n}(x)=1+p \int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{\tau d^{2} y_{n}}{d \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} 2 \frac{d y_{n}}{d \tau}+\sum_{n=0}^{\infty} p^{(n)} \alpha\left(\tau^{m+1} \ln \tau\right) y_{n}\right) d \tau$,

Now, comparing the co-efficient of like powers of $p$,

$$
\begin{aligned}
& p^{(0)}: \quad y_{0}=1, \\
& p^{(1)}: \quad y_{1}=\int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\alpha \tau^{m+1} \ln \tau y_{0}\right) d \tau \\
&=\frac{\alpha x^{m+2}(5+2 m-(m+2)(m+3) \ln x)}{(m+2)^{2}(m+3)^{2}} \\
& p^{(2)}: \quad y_{2}=\int_{0}^{x}\left(\frac{\tau}{x}-1\right)\left(\frac{\tau d^{2} y_{1}(\tau)}{d \tau^{2}}+2 \frac{d y_{1}}{d \tau}+\alpha \tau^{m+1} \ln \tau y_{1}\right) d \tau \\
&=\frac{\alpha x^{2 m+4}}{4} \frac{\lambda-\mu \ln x-\eta(\ln x)^{2}}{(2 m+3)^{3}(m+3)^{2}(m+2)^{4}} \\
& \vdots
\end{aligned}
$$

where

$$
\begin{aligned}
& \lambda=408+503 m+206 m^{2}+28 m^{3} \\
& \mu=2(2 m+5)(m+2)\left(8 m^{2} 41 m+52\right) \\
& \eta=2(2 m+5)^{2}(m+3)(m+2)^{2}
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
y(x)==1+\frac{\alpha x^{m+2}(5+2 m-(m+2)(m+3) \ln x)}{(m+2)^{2}(m+3)^{2}}+\frac{\alpha x^{2 m+4}}{4} \frac{\lambda-\mu \ln x-\eta(\ln x)^{2}}{(2 m+3)^{3}(m+3)^{2}(m+2)^{4}}+\cdots \tag{21}
\end{equation*}
$$

where $m \neq-2,-3,-\frac{3}{2}, \cdots$. The exact solutions are exist for $r=0$ and $m=-1,0,1,2,3$, respectively.

$$
\begin{align*}
& y(x)=1-\frac{\alpha x}{2}\left(\ln x-\frac{3}{2}\right) \\
& y(x)=1-\frac{\alpha x^{2}}{6}\left(\ln x-\frac{5}{6}\right) \\
& y(x)=1-\frac{\alpha x^{3}}{12}\left(\ln x-\frac{7}{12}\right) .  \tag{22}\\
& y(x)=1-\frac{\alpha x^{4}}{20}\left(\ln x-\frac{9}{20}\right) . \\
& y(x)=1-\frac{\alpha x^{5}}{30}\left(\ln x-\frac{11}{30}\right) .
\end{align*}
$$

## VIMAP

According to VIMAP, Eq. (18) can be written in the form,

$$
\begin{equation*}
y_{n+1}(x)=y_{0}(x)+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}+\alpha \tau^{m} \ln \tau \sum_{n=0}^{\infty} A_{n}(\tau)\right) d \tau \tag{23}
\end{equation*}
$$

The initial approximation is reads as

$$
y_{0}=y(0)=1,
$$

Consequently, we have

$$
\begin{aligned}
& y_{1}(x)=1+\frac{\alpha x^{m+2}(5+2 m-(m+2)(m+3) \ln x)}{(m+2)^{2}(m+3)^{2}} \\
& y_{2}(x)=1+\frac{\alpha x^{m+2}(5+2 m-(m+2)(m+3) \ln x)}{(m+2)^{2}(m+3)^{2}}+\frac{\alpha r x^{2 m+4}}{4} \frac{\lambda-\mu \ln x-\eta(\ln x)^{2}}{(2 m+3)^{3}(m+3)^{2}(m+2)^{4}}
\end{aligned}
$$

where

$$
\lambda=408+503 m+206 m^{2}+28 m^{3}
$$

$$
\begin{aligned}
& \mu=2(2 m+5)(m+2)\left(8 m^{2} 41 m+52\right) \\
& \eta=2(2 m+5)^{2}(m+3)(m+2)^{2}
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
y(x)==1+\frac{\alpha x^{m+2}(5+2 m-(m+2)(m+3) \ln x)}{(m+2)^{2}(m+3)^{2}}+\frac{\alpha r x^{2 m+4}}{4} \cdot \frac{\lambda-\mu \ln x-\eta(\ln x)^{2}}{(2 m+3)^{3}(m+3)^{2}(m+2)^{4}}+\cdots, \tag{24}
\end{equation*}
$$

where $m \neq-2,-3,-\frac{3}{2}, \cdots$. the exact solutions are exists for $r=0$ and $m=-1,0,1,2,3$. respectively.

$$
\begin{align*}
& y(x)=1-\frac{\alpha x}{2}\left(\ln x-\frac{3}{2}\right) \\
& y(x)=1-\frac{\alpha x^{2}}{6}\left(\ln x-\frac{5}{6}\right) . \\
& y(x)=1-\frac{\alpha x^{3}}{12}\left(\ln x-\frac{7}{12}\right) .  \tag{25}\\
& y(x)=1-\frac{\alpha x^{4}}{20}\left(\ln x-\frac{9}{20}\right) . \\
& y(x)=1-\frac{\alpha x^{5}}{30}\left(\ln x-\frac{11}{30}\right) .
\end{align*}
$$

Plot of graphical representation of solution (25) are:


Fig. 2

### 5.3 Example

Consider a linear homogeneous Lane-Emden Equation

$$
\begin{equation*}
\frac{d^{2} y}{d x^{2}}+\frac{2}{x} \frac{d y}{d x}-\left(4 x^{2}+6\right) y=.0 \tag{26}
\end{equation*}
$$

Subject to the conditions

$$
y(0)=1, y^{\prime}(0)=0 .
$$

## VIMAP

According to VIM, the correction functional for the equation (26) can be written as

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x} \lambda(\tau)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}-\left(4 \tau^{2}+6\right) \tilde{y}_{n}\right) d \tau \tag{27}
\end{equation*}
$$

The Lagrange Multiplier can be identified via variational theory.

$$
\lambda(x, \tau)=\frac{\tau^{2}}{x}-\tau,
$$

Now Eq. (27) becomes

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}-\left(4 \tau^{2}+6\right) y_{n}\right) d \tau \tag{28}
\end{equation*}
$$

According to VIMHP, equation (28) can be written as,

$$
\begin{aligned}
& \sum_{n=0}^{\infty} p^{(n)} y_{n}(x)=y_{0}+p \int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{d^{2} y_{n}}{d \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} \frac{2}{\tau} \frac{d y_{n}}{d \tau}-\left(4 \tau^{2}+6\right) \sum_{n=0}^{\infty} p^{(n)} y_{n}\right) d \tau \\
& \sum_{n=0}^{\infty} p^{(n)} y_{n}(x)=1+p \int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{d^{2} y_{n}}{d \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} \frac{2}{\tau} \frac{d y_{n}}{d \tau}-\left(4 \tau^{2}+6\right) \sum_{n=0}^{\infty} p^{(n)} y_{n}\right) d \tau
\end{aligned}
$$

Comparing the coefficients of like powers of $p$ :

$$
p^{(0)}: \quad y_{0}=1
$$

$$
\begin{array}{ll}
p^{(1)}: & y_{1}=x^{2}+\frac{x^{4}}{5} \\
p^{(2)}: & y_{2}=\frac{3}{10} x^{4}+\frac{13}{105} x^{6}+\frac{1}{90} x^{8}, \\
p^{(3)}: & y_{3}=\frac{3}{70} x^{6}+\frac{17}{630} x^{8}+\frac{59}{11550} x^{10}+\frac{1}{3510} x^{12}, \\
\vdots &
\end{array}
$$

Therefore the closed form solution is

$$
\begin{equation*}
y(x)=e^{x^{2}} . \tag{29}
\end{equation*}
$$

This is the exact solution of the Lane-Emden equation.

## VIMAP

According to VIMAP, Eq. (26) can be written as,

$$
\begin{equation*}
y_{n+1}(x)=y_{n}(x)+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{d^{2} y_{n}(\tau)}{d \tau^{2}}+\frac{2}{\tau} \frac{d y_{n}}{d \tau}-\left(4 \tau^{2}+6\right) y_{n}\right) d \tau \tag{30}
\end{equation*}
$$

The initial approximation is reads as

$$
y_{0}=y(0)=1,
$$

Consequently, we have

$$
\begin{aligned}
& y_{1}=1+x^{2}+\frac{x^{4}}{5} \\
& y_{2}=1+x^{2}+\frac{x^{4}}{5}+\frac{3}{10} x^{4}+\frac{13}{105} x^{6}+\frac{1}{90} x^{8}, \\
& y_{3}=1+x^{2}+\frac{x^{4}}{5}+\frac{3}{10} x^{4}+\frac{13}{105} x^{6}+\frac{1}{90} x^{8}+\frac{3}{70} x^{6}+\frac{17}{630} x^{8}+\frac{59}{11550} x^{10}+\frac{1}{3510} x^{12}, \\
& \vdots
\end{aligned}
$$

The closed solution is

$$
y(x)=e^{x^{2}}
$$

This is solution of the Lane-Emden equation; this result is same as obtained [18].
Graphical representation of the solution is:


Fig. 3

### 5.4 Example

Consider a Time-Dependent Lane-Emden equation

$$
\begin{equation*}
\frac{\partial^{2} y}{\partial x^{2}}+\frac{2}{x} \frac{\partial y}{\partial x}-\left(6+4 x^{2}-\cos t\right) y=\frac{\partial y}{\partial t} \tag{31}
\end{equation*}
$$

subject to the condition

$$
y(0, t)=e^{\sin t}, \quad y_{x}(0, t)=0
$$

## VIMHP

According to VIM, the correction functional for the equation (31) can be written as

$$
\begin{equation*}
y_{n+1}(x, t)=y_{n}+\int_{0}^{x} \lambda\left(\frac{\partial^{2} y_{n}}{\partial \tau^{2}}+\frac{2}{\tau} \frac{\partial y_{n}}{\partial \tau}-\left(6+4 \tau^{2}-\cos t\right) \tilde{y}_{n}-\frac{\partial \tilde{y}_{n}}{\partial t}\right) d \tau \tag{32}
\end{equation*}
$$

where $\lambda$ is called general Lagrange multiplier, which can be identified as

$$
\lambda(x, \tau)=\frac{\tau^{2}}{x}-\tau
$$

Therefore, Eq. (32) becomes

$$
\begin{equation*}
y_{n+1}(x, t)=y_{n}+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{\partial^{2} y_{n}}{\partial \tau^{2}}+\frac{2}{\tau} \frac{\partial y_{n}}{\partial \tau}-\left(6+4 \tau^{2}-\cos t\right) y_{n}-\frac{\partial y_{n}}{\partial t}\right) d \tau \tag{33}
\end{equation*}
$$

According to VIMHP, Eq. (33) can be written as,

$$
\begin{aligned}
& \sum_{n=0}^{\infty} p^{(n)} y_{n}(x, t)=y_{0}+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{\partial^{2} y_{n}}{\partial \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} \frac{2}{\tau} \frac{\partial y_{n}}{\partial \tau}-\left(6+4 \tau^{2}-\cos t\right) \sum_{n=0}^{\infty} p^{(n)} y_{n}-\sum_{n=0}^{\infty} p^{(n)} \frac{\partial y_{n}}{\partial t}\right) d \tau \\
& \sum_{n=0}^{\infty} p^{(n)} y_{n}(x, t)=e^{\sin t}+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\sum_{n=0}^{\infty} p^{(n)} \frac{\partial^{2} y_{n}}{\partial \tau^{2}}+\sum_{n=0}^{\infty} p^{(n)} \frac{2}{\tau} \frac{\partial y_{n}}{\partial \tau}-\left(6+4 \tau^{2}-\cos t\right) \sum_{n=0}^{\infty} p^{(n)} y_{n}-\sum_{n=0}^{\infty} p^{(n)} \frac{\partial y_{n}}{\partial t}\right) d \tau
\end{aligned}
$$

Comparing the co-efficient of like powers of $p$ :

$$
\begin{array}{ll}
p^{(0)}: & y_{0}=e^{\sin t}, \\
p^{(1)}: & y_{1}=e^{\sin t}\left(x^{2}+\frac{x^{4}}{5}\right) \\
p^{(2)}: & y_{2}=e^{\sin t}\left(\frac{3}{10} x^{4}+\frac{13}{105} x^{6}+\frac{x^{8}}{90}\right),
\end{array}
$$

Thus, the closed form solution is

$$
\begin{align*}
y(x, t) & =e^{\sin t}\left(1+x^{2}+\frac{x^{4}}{2!}+\frac{x^{6}}{3!}+\frac{x^{8}}{4!}+\cdots,\right),  \tag{34}\\
& =e^{x^{2}+\sin t}
\end{align*}
$$

This is the same result as obtained by A. Sami Bataineh, M. S. M. Noorani, and I. Hashim in [19].
VIMAP
According to VIMAP, the Eq. (31) becomes

$$
\begin{equation*}
y_{n+1}(x, t)=y_{n}+\int_{0}^{x}\left(\frac{\tau^{2}}{x}-\tau\right)\left(\frac{\partial^{2} y_{n}}{\partial \tau^{2}}+\frac{2}{\tau} \frac{\partial y_{n}}{\partial \tau}-\left(6+4 \tau^{2}-\cos t\right) y_{n}-\frac{\partial y_{n}}{\partial t}\right) d \tau \tag{35}
\end{equation*}
$$

The initial approximate solution is reads as

$$
y_{0}=y(0, t)=e^{\sin t},
$$

Consequently, we have

$$
\begin{aligned}
& y_{1}=e^{\sin t}+e^{\sin t}\left(x^{2}+\frac{x^{4}}{5}\right) \\
& y_{2}=e^{\sin t}+e^{\sin t}\left(x^{2}+\frac{x^{4}}{5}\right)+e^{\sin t}\left(\frac{3}{10} x^{4}+\frac{13}{105} x^{6}+\frac{x^{8}}{90}\right) \\
& y_{3}=e^{\sin t}+e^{\sin t}\left(x^{2}+\frac{x^{4}}{5}\right)+e^{\sin t}\left(\frac{3}{10} x^{4}+\frac{13}{105} x^{6}+\frac{x^{8}}{90}\right)+e^{\sin t}\left(\frac{3 x^{6}}{70}+\frac{17 x^{8}}{630}+\frac{54 x^{10}}{11550}+\frac{1}{3510} x^{12}\right), \\
& \vdots
\end{aligned}
$$

Thus, the close form solution is

$$
\begin{equation*}
y(x, t)=e^{x^{2}+\sin t} \tag{36}
\end{equation*}
$$

This is the same result as obtained by A. Sami Bataineh, M.S.M. Noorani, and I. Hashim [19].
Plot of graphical representation of the solution:


Fig. 4

In this paper, two modifications of Variational Iteration Method (VIM) are implemented successfully to obtain the analytical exact and approximate solutions of two nonlinear mathematical problems. The solution procedure is very simple by means of variatonal theory, and only a few steps lead to highly accurate solutions. It has been observed that these modifications are very efficient and reliable for the solution of the non-linear problems.

## References

[1] M. A. Abdou and A. A. Soliman, New applications of Variational iteration method, Phys. D 211, pages 1-8, 2005.
[2] S. Abbasbandy, A new application of He's Variational Iteration method for quadratic Riccati differential equation by using Adomian's polynomials, J. Comp. Appl. Math. 207, pages 5963, 2007.
[3] T. A. Abassy, M. A. El-Tawil and H. El-Zoheiry, Solving nonlinear partial Differential equations using the modified Variational iteration Pade' technique, J. Comp. Appl. Math 207, pages 73-91, 2007.
[4] S. T. Mohyud-Din and M. A. Noor, Homotopy perturbation method for solving partial differential equations, ZeitschriftfürNaturforschung A, 64a, pages 1-14, 2008.
[5] S. T. Mohyud-Din, M. A. Noor and K. I. Noor, Solution of singular equations by He's variational iteration method, Int. J. Nonlin. Sci. Num. Sim. Pages 10-121, 2009.
[6] M. A. Noor and S. T. Mohyud-Din, Solution of singular and nonsingular initial and boundary value problems by modified Variational iteration method, Math. Prob. Eng. Article ID 917407, 23 pages, doi:10.1155/2008/917407, 2008.
[7] M. Inokuti, H. Sekine and T. Mura, General use of the Lagrange multiplier in nonlinear mathematical physics, in: S. Nemat-Naseer (Ed.), Variational Method in the Mechanics of Solids, Pergamon press, New York, pages 156-162, 1978.
[8] j. Ahmad, Q. M. Hassan and S. T. mohyud-Din, Solitary solutions of the fractional KdV equation using modified Reimann-Liouville derivative, Vol. 4(2), pages 349-356, 2013.
[9] N. H. Sweilam, Harmonic wave solutions in nonlinear thermo elasticity by variational iteration method and Adomian's method, J. Comput. Appl. Math. 207, pages 64-72, 2007.
[10] J. H. He, an elementary introduction of recently developed asymptotic methods and nanomechanics in textile engineering, Int. J. Mod. Phys. B 22 (21), pages 3487-4578, 2008.
[11] A. Ghorbani and J. S. Nadjfi, He's homotopy perturbation method for calculating Adomian's polynomials, Int. J. Nonlinear Sci. Num. Simul. 8 (2), pages 229-332, 2007.
[12] J. H. He, recent developments of the homotopy perturbation method, Top. Meth. Nonlinear Anal. 3, pages 1205-209, 2008.
[13] J. H. He, Homotopy perturbation technique, Comp. Math. Appl. Mech, Engy., pages178-257, 1999.
[14] J. H. He, Comparison of homotopy perturbation method and homotopy analysis method, Appl. Math. Comp. 156, pages 527-539, 2004.
[15] S. T. Mohyud-Din, M. A. Noor and K. I. Noor, Variational iteration method for solving FlierlPetviashivili equation using He's polynomials and Pade' approximants, ActaMathematicaScientia, 2009.
[16] S. T. Mohyud-Din, M. A. Noor and K. I. Noor, Modified Variational iteration method for solving Sine Gordon equations, Wd. Appl. Sci. J. 2008.
[17]J. Biazar and S. M. Shafiof, A simple algorithm for calculation Adomian polynomials, int. Contemp. Math. Science, Vol. 2, no. 20, pages 975-982, 2007.
[18]M. S. H. Chowdhury, I. Hashim, Solutions of Emden-Fowler equations by homotopyperturbation method, Nonlinear Analysis: Real World Applications 10, pages 104-115, 2009.
[19] A. Sami Bataineh, M. S. M. Noorani, I. Hashim, Solution of time-dependent Emden-Fowler type equation by Homotopy Analysis Method, Physics Letters. A 371, pages 72-82, 2007.


[^0]:    * Corresponding Author: jamshadahmadm@gmail.cm (J. Ahmad)

