#### LOAD TEST OF 0.5HP AC INDUCTION MOTOR USING COUPLING SYSTEM

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MAY 2011

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## SCHOOL OF ELECTRICAL SYSTEMS ENGINEERING UNIVERSITY MALAYSIA PERLIS

2011

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#### **DECLARATION SHEET**

I hereby declare that my Final Year Project Thesis is the result of my research work under supervision of ANAYET KARIM. All literature sources used for the writing of this thesis have been adequately referenced.

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#### APPROVAL AND DECLARATION SHEET

This project report titled Load Test of 0.5HP AC Induction Motor Using Coupling System was prepared and submitted by Ting Siu Hui (Matrix Number: 071091278) and has been found satisfactory in terms of scope, quality and presentation as partial fulfillment of the requirement for the Bachelor of Engineering (Electrical Systems Engineering) in Universiti Malaysia Perlis (UniMAP).

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May 2011

#### UJIAN BEBAN PENJANA MOTOR DENGAN MENGGUNAKAN SISTEM SINAPSIS

#### ABSTRAK

Penjana motor digunakan di seluruh dunia sebagar pekerja dalam aplikasi industri seperti kipas, pam, peralatan mesin, lif dan alat pengangkutan. Penjana motor mempunyai ciri-ciri yang ringkas dan pelbagai, mudah diservis, mempunyai kecekapan yang tinggi dan harganya adalah berpatutan. Ciri-ciri ini mendorong kepada standardisasi dan perkembangan motor dalam bidang pembuatan dan infrastruktur dan diperkenalkan secara meluas dalam pelbagai bidang. Oleh itu, usaha untuk meningkatkan kecekapan motor akan memberikan kesan yang positif dalam mengurangkan pembaziran tenaga elektrik terutamanya dalam bidang industri. Terdapat pelbagai kaedah yang boleh dipakai untuk menentukan kecekapan penjana motor. Antaranya adalah menjalankan ujian tanpa beban, ujian angkir terkunci, ujian rintangan arus terus dan ujian beban terhadap penjana motor untuk mendapatkan berbagai-bagai nilai yang dikehendaki. Pengiraan akan dijalankan untuk menentukan spesifikasi penjana motor seperti nilai rintangan keseluruhan, kebocoran galangan, kehilangan kuasa, arus dan lain-lain. Akhirnya, kecekapan penjana motor dapat ditentukan.

#### LOAD TEST OF 0.5HP AC INDUCTION MOTOR USING COUPLING SYSTEM

#### ABSTRACT

Induction motors are used worldwide as the workhorse in industrial application such as fan, pumps, machine tools, elevators and conveyors. It offers users simplicity, rugged construction, easy maintenance, relatively high efficiency and cost effective pricing. These factors have promoted standardization and development of a manufacturing infrastructure that has led to a vast installed base of motors. Thus, improvements in the efficiency of the electrical drives would offer significant effects in reducing industrial electrical energy usage. There are various types of method in determining the efficiency of induction motors. Among them are No-Load Test, Blocked Rotor Test, DC Resistance Test and Load Test for rotating machine to get various data on the induction motor. A proper parameter calculation need to be carried on to obtain the range of specification of the induction motor such as the total resistance, the leakage impedances, the losses estimation, stator current, rotor current and so on. Finally, the efficiency of the AC Induction Motor is determined.

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#### LIST OF SYMBOLS, ABBREVIATIONS OR NOMENCLATURE

| EMF                   | Electromagnetic Force                         |
|-----------------------|---|
| η                     | Efficiency                                    |
| NEMA                  | National Electrical Manufacturers Association |
| <i>I</i> <sub>1</sub> | Stator Current                                |
| PF                    | Power Factor                                  |
| S                     | Slip  |
| Нр                    | Horsepower                                    |
| $P_{F\&W}$            | Friction and Windage Losses                   |
| n <sub>s</sub>        | Synchronous Speed                             |
| kVAR                  | Kilo Volt-Amperes-Reactive                    |
| kW                    | Kilowatt                                      |
| kVA                   | Kilovolts-Amperes                             |
| $I_L$                 | Line Current                                  |
| $V_{L-L}$             | Line-to-Line Voltage                          |
| I <sub>X</sub>        | Reactive Component                            |
| I <sub>P</sub>        | Load Component current                        |
| θ                     | Electrical Angle                              |
| P <sub>in</sub>       | Input Power                                   |
| Pout                  | Output Power                                  |
| P <sub>rot</sub>      | Rotational Losses                             |
| P <sub>mec h</sub>    | Mechanical Power                              |
| $P_{AG}$              | Air Gap power                                 |
| <i>R</i> <sub>2</sub> | Rotor Resistance                              |
| P <sub>core</sub>     | Core Losses                                   |
| $P_{NL}$              | No-Load Power                                 |
| I <sub>NL</sub>       | No-Load Current                               |
| $R_{NL}$              | No-Load Resistance                            |

| $Z_{NL}$                  | No-Load Impedance                              |
|---------------------------|--|
| <i>R</i> <sub>1</sub>     | Stator Resistance                              |
| <i>X</i> <sub>1</sub>     | Stator Leakage Reactance                       |
| <i>X</i> <sub>2</sub>     | Rotor Leakage Reactance                        |
| $X_m$                     | Magnetizing Reactance                          |
| $P_{BR}$                  | Blocked Rotor Power                            |
| I <sub>BR</sub>           | Blocked Rotor Current                          |
| $R_{BR}$                  | Blocked Rotor Resistance                       |
| $Z_{BR}$                  | Blocked Rotor Impedance                        |
| X <sub>BR</sub>           | Blocked Rotor Reactance                        |
| V <sub>dc</sub>           | DC Voltage                                     |
| <i>I</i> <sub>dc</sub>    | DC Current                                     |
| I <sub>c</sub>            | Per-Phase Stator Core Loss Current             |
| <i>I</i> <sub>m</sub>     | Magnetizing Current                            |
| $R_c$                     | Per-Phase Stator Core Loss Resistance          |
| $L_m$                     | Per-Phase Stator Magnetizing Inductance        |
| $V_p$                     | Phase Voltage                                  |
| P <sub>core</sub>         | Core Losses                                    |
| P <sub>SCL</sub>          | Stator Copper Losses                           |
| P <sub>RCL</sub>          | Rotor Copper Losses                            |
| $f_t$                     | Frequency of the Blocked-Rotor Test Voltage    |
| f <sub>B</sub>            | Rated Frequency                                |
| P <sub>stray</sub> (IEEE) | Stray Load Losses Based On IEEE 112-B Standard |
| P                         | True Power                                     |
| Q                         | Reactive Power                                 |
| S                         | Apparent Power                                 |
| <i>n<sub>slip</sub></i>   | Slip Speed                                     |
| $n_m$                     | Mechanical Shaft Speed                         |
| W <sub>sync</sub>         | Synchronous Angular Velocity                   |
| W <sub>m</sub>            | Mechanical Angular velocity                    |